

# An Algebraic Theory of Conditioning

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# How to express dependence on data?

## Scoring

```
position = normal(0, 100)
observe(normal(position, 5), 42)
```

i.e.

```
score(pdf_normal(position, 5)(42))
```

[Stan, WebPPL]

vs

## Exact Conditioning

```
# generative model
position = normal(0, 100)
measurement = normal(position, 5)

# conditioning
measurement ::= 42
```

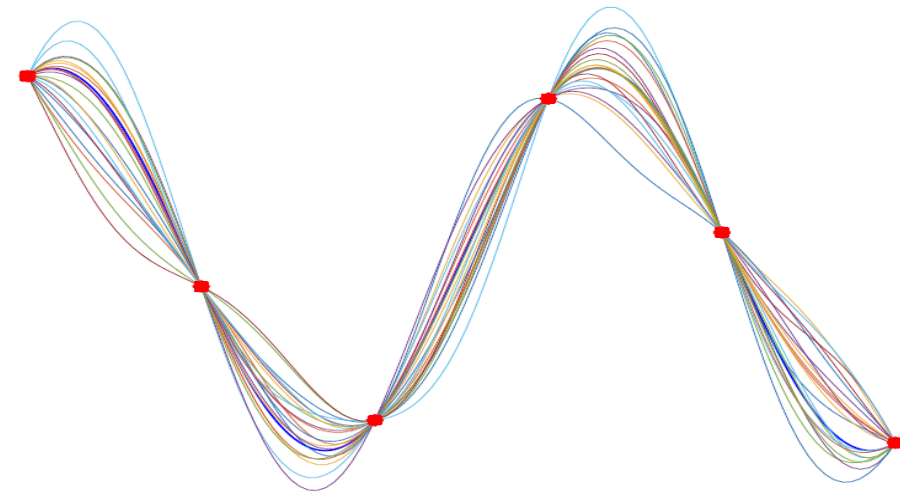
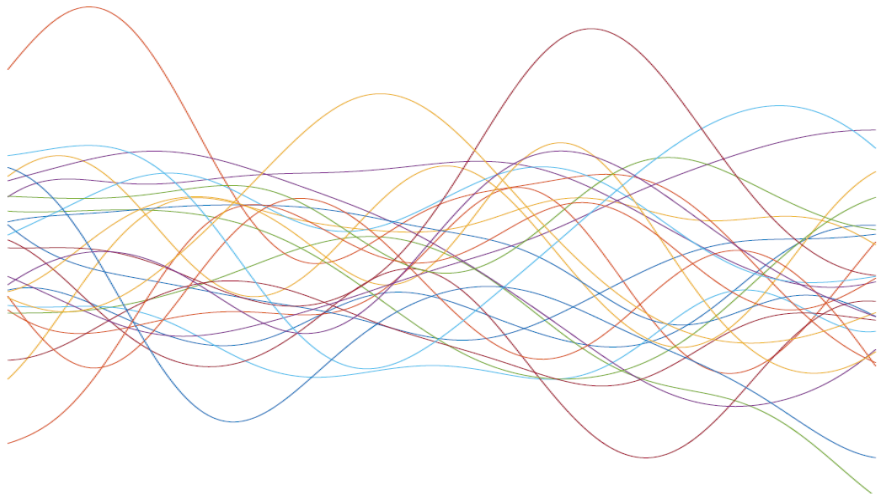
[Hakaru, Infer.NET]

# Advantages of Exact Conditioning

- Modularity

*scoring statements would need to be interleaved with `gp_sample`*

```
ys = gp_sample(n=100, kernel=rbf)
for (i,obs) in observations:
  ys[i] ::= obs
```



# Advantages of Exact Conditioning

- Intuitiveness & Correctness

```
x = normal(0,1)
y = normal(0,1)
x ::= y
```

provably equal

```
x = normal(0,sqrt(1/2))
y = x

# x = y holds exactly
```

Closest approximation using scoring ...

```
x = normal(0,1)
y = normal(0,1)

observe(normal(0,0.01), x-y)

# x = y does not hold!
# why 0.01?
```

# A language for exact conditioning

- Toy language: Only Gaussians & affine maps + conditioning
  - Kalman filters, Ridge regression, Gaussian processes
- Reference implementation
  - Calling `normal( $\mu, \sigma$ )` allocates a latent RV
  - Maintain a joint prior over all RVs
  - When conditioning, update the prior
    - Symbolic inference: Gaussians are self-conjugate

```
import numpy as np
import scipy.linalg as linalg

class Gauss:

    def __init__(self, dom, cod, A=None, b=None, Sigma=None):
        self.dom = dom
        self.cod = cod

        self.A = A if A is not None else np.zeros((cod, dom))
        self.b = b if b is not None else np.zeros(cod)
        self.Sigma = Sigma if Sigma is not None else np.zeros((dom, dom))

    # Condition on the first n variables
    # cond : (a -> n + k) -> (a + n -> k)
    def cond(self, n):
        m = self.cod - n
        SigmaX = self.Sigma[0:n, 0:n]
        SigmaY = self.Sigma[n:, n:]
        SigmaYX = self.Sigma[n:, 0:n]
        M = self.A[0:n, :]
        N = self.A[n:, :]
        s = self.b[0:n]
        t = self.b[n:]

        SXi = np.linalg.pinv(SigmaX)
        D = SigmaYX.dot(SXi)
        A = np.block([D, N - D.dot(M)])
        b = t - D.dot(s)
        S = SigmaY - D.dot(SigmaYX.T)
        return Map(A, b, S)
```

# Verifying properties

## Commutativity

$A1 ::= A2$   
 $B1 ::= B2$

$\approx?$

$B1 ::= B2$   
 $A1 ::= A2$



## Substitutivity

$x ::= y ; c[x]$

$\approx?$

$x ::= y ; c[y]$



## Equivalent conditions

$2x ::= -4y + 2$

$\approx?$

$x + 2y ::= 1$



## MIND BOREL'S PARADOX!

[Shan]

$x/y ::= 1$

~~$\approx?$~~

$x - y ::= 0$

# Hard questions

- How to generalize to a *non-toy language*?
- Which nice behavior transfers?
- What should the general properties of ( $\equiv$ ) be?

## **WANTED:**

General<sup>1</sup> compositional<sup>2</sup> semantics for exact conditioning

# I. General

- Exact conditioning on continuous variables is hard
  - Borel's paradox & [Jules Jacobs, POPL'21]
- Conditioning is about ...
  - Densities ✘
  - Limits ✘
  - Measure Theory ✘
  - **Universal property** → **Markov categories** [Fritz, Cho&Jacobs] ✔



## II. Compositional

- Markov category conditionals are still a transformation of whole (closed) programs
- *Cond-construction*: Explain equivalence of *open programs*

```
x |- let y = normal(0,1) in x ::= y; return (x,y)
```

Markov categories + Cond-construction  
= Compositional Exact Conditioning

# Summary

- Language for Gaussian conditioning with good properties
- Those good properties generalize!
  - Conditioning via universal properties
- Markov categories + Cond = Compositional Exact Conditioning
  - Denotational semantics for symbolic disintegration [Shan]
- Study well-behaved Markov categories!

# Bonus

- We can fully axiomatize the Gaussian language!
- The only things you need to know is
  - The language is commutative & discardable
  - IID Gaussians are invariant under rotations
  - Nice laws for conditioning

$$a, b \mid \varphi : 1 \vdash (a = b); \varphi[a] \equiv (a = b); \varphi[b] \quad (10)$$

$$a, b \mid \varphi : 1 \vdash (a = b); \nu x. \varphi[x] \equiv \nu x. (a = b); \varphi[x] \quad (11)$$

$$- \mid \varphi : 1 \vdash \nu x. (x = \underline{c}); \varphi[x] \equiv \varphi[\underline{c}] \quad (12)$$

**BBonus:** There is no Borel's paradox in Gaussian probability